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(%i1) /* define special summation function */
f(i,j) := sum(R[i,j,sigma,0]*gContr[i,sigma]*gContr[j,0],sigma,0,3)
      + sum(R[i,j,sigma,1]*gContr[i,sigma]*gContr[j,1],sigma,0,3)
      + sum(R[i,j,sigma,2]*gContr[i,sigma]*gContr[j,2],sigma,0,3)
      + sum(R[i,j,sigma,3]*gContr[i,sigma]*gContr[j,3],sigma,0,3);

(%o1) f(i, j) := sum(Ri, j, σ, 0 gContri, σ gContrj, 0, σ, 0, 3) +
sum(Ri, j, σ, 1 gContri, σ gContrj, 1, σ, 0, 3) +
sum(Ri, j, σ, 2 gContri, σ gContrj, 2, σ, 0, 3) +
sum(Ri, j, σ, 3 gContri, σ gContrj, 3, σ, 0, 3)

(%i2) /* define coordinate vector */
array(x, 3);
[x[0],x[1],x[2],x[3]]: [t, r, theta, phi];

(%o2) x

(%o3) [ t , r , θ , φ ]

(%i4) /* g1 is symm. metric with indices 1...4 */
/* ***** Ciufolini - Wheeler (6.1.1)
weak field, slow motion limit 2nd variant **** */
g1: matrix(
[-(1-2*M/r),0,0,-4*J/r*sin(theta)^2],
[0,(1-2*M/r)^{-1},0,0],
[0,0,r^2,0],
[-4*J/r*sin(theta)^2,0,0,r^2*sin(theta)^2]
);

(%o4) 
$$\begin{bmatrix} \frac{2M}{r}-1 & 0 & 0 & -\frac{4\sin(\theta)^2 J}{r} \\ 0 & \frac{1}{1-\frac{2M}{r}} & 0 & 0 \\ 0 & 0 & r^2 & 0 \\ -\frac{4\sin(\theta)^2 J}{r} & 0 & 0 & r^2\sin(\theta)^2 \end{bmatrix}$$


(%i5) /* contravariant g is inverse of g */
gContr1: ratsimp(invert(g1));
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$$(\% 05) \begin{bmatrix} \frac{r^4}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4} & 0 & 0 & \frac{4 r J}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4} \\ 0 & -\frac{2 M - r}{r} & 0 & 0 \\ 0 & 0 & \frac{1}{r^2} & 0 \\ \frac{4 r J}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4} & 0 & 0 & \frac{2 r M - r^2}{2 r^3 \sin(\theta)^2 M - 16 \sin(\theta)^4 J^2 - r^4 \sin(\theta)^2} \end{bmatrix}$$

(%i6)

```
/* g1 and gContr1 are transformed to g and gContr (indices 0...3) */
for mu:0 thru 3 do {
for nu:0 thru 3 do {
g [mu,nu] : g1 [mu+1, nu+1],
gContr [mu,nu] : gContr1 [mu+1, nu+1]
}}$
```

```
(%i7) /* computation of Christoffel symbols Gamma^sigma_mu_nu */
for sigma:0 thru 3 do {
for mu:0 thru 3 do {
for nu:0 thru 3 do {
Gamma [sigma,mu,nu] :
/* rho sum by function call: */
sum(
1/2 * gContr [sigma,rho] *(
diff(g [nu,rho],x [mu]) +
diff(g [rho,mu],x [nu]) -
diff(g [mu,nu],x [rho])),
rho, 0, 3),
/* evaluate differentiation dy/dr */
Gamma [sigma,mu,nu] : ev(Gamma [sigma,mu,nu], diff)
}}}$
```

```
(%i8) /* display Gamma's being different from zero */
for i:0 thru 3 do {
for j:0 thru 3 do {
for k:0 thru 3 do {
if Gamma [i,j,k] # 0 then {
display(Gamma [i,j,k])
}}}$
```

$$\Gamma_{0,0,1} = \frac{8 \sin(\theta)^2 J^2}{r(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} - \frac{r^2 M}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4}$$

$$\Gamma_{0,0,2} = -\frac{16 \cos(\theta) \sin(\theta) J^2}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4}$$

$$\Gamma_{0,1,0} = \frac{8 \sin(\theta)^2 J^2}{r(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} - \frac{r^2 M}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4}$$

$$\Gamma_{0,1,3} = \frac{6 r^2 \sin(\theta)^2 J}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4}$$

$$\Gamma_{0,2,0} = -\frac{16 \cos(\theta) \sin(\theta) J^2}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4}$$

$$\Gamma_{0,3,1} = \frac{6 r^2 \sin(\theta)^2 J}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4}$$

$$\Gamma_{1,0,0} = -\frac{M(2M - r)}{r^3}$$

$$\Gamma_{1,0,3} = \frac{2 \sin(\theta)^2 J(2M - r)}{r^3}$$

$$\Gamma_{1,1,1} = \frac{M(2M - r)}{r^3 \left(1 - \frac{2M}{r}\right)^2}$$

$$\Gamma_{1,2,2} = 2M - r$$

$$\Gamma_{1,3,0} = \frac{2 \sin(\theta)^2 J(2M - r)}{r^3}$$

$$\Gamma_{1,3,3} = \sin(\theta)^2 (2M - r)$$

$$\Gamma_{2,0,3} = \frac{4 \cos(\theta) \sin(\theta) J}{r^3}$$

$$\Gamma_{2,1,2} = \frac{1}{r}$$

$$\Gamma_{2,2,1} = \frac{1}{r}$$

$$\Gamma_{2,3,0} = \frac{4 \cos(\theta) \sin(\theta) J}{r^3}$$

$$\Gamma_{2,3,3} = -\cos(\theta) \sin(\theta)$$

$$\Gamma_{3,0,1} = \frac{2 \sin(\theta)^2 J(2rM - r^2)}{r^2(2r^3 \sin(\theta)^2 M - 16 \sin(\theta)^4 J^2 - r^4 \sin(\theta)^2)} - \frac{4JM}{r(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)}$$

$$\Gamma_{3,0,2} = -\frac{4 \cos(\theta) \sin(\theta) J(2rM - r^2)}{r(2r^3 \sin(\theta)^2 M - 16 \sin(\theta)^4 J^2 - r^4 \sin(\theta)^2)}$$

$$\Gamma_{3,1,0} = \frac{2 \sin(\theta)^2 J(2rM - r^2)}{r^2(2r^3 \sin(\theta)^2 M - 16 \sin(\theta)^4 J^2 - r^4 \sin(\theta)^2)} - \frac{4JM}{r(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)}$$

$$\Gamma_{3,1,3} = \frac{r \sin(\theta)^2 (2rM - r^2)}{2r^3 \sin(\theta)^2 M - 16 \sin(\theta)^4 J^2 - r^4 \sin(\theta)^2} + \frac{8 \sin(\theta)^2 J^2}{r(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)}$$

$$\Gamma_{3,2,0} = -\frac{4 \cos(\theta) \sin(\theta) J(2rM - r^2)}{r(2r^3 \sin(\theta)^2 M - 16 \sin(\theta)^4 J^2 - r^4 \sin(\theta)^2)}$$

$$\Gamma_{3,2,3} = \frac{r^2 \cos(\theta) \sin(\theta) (2 r M - r^2)}{2 r^3 \sin(\theta)^2 M - 16 \sin(\theta)^4 J^2 - r^4 \sin(\theta)^2} - \frac{16 \cos(\theta) \sin(\theta) J^2}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4}$$

$$\Gamma_{3,3,1} = \frac{r \sin(\theta)^2 (2 r M - r^2)}{2 r^3 \sin(\theta)^2 M - 16 \sin(\theta)^4 J^2 - r^4 \sin(\theta)^2} + \frac{8 \sin(\theta)^2 J^2}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)}$$

$$\Gamma_{3,3,2} = \frac{r^2 \cos(\theta) \sin(\theta) (2 r M - r^2)}{2 r^3 \sin(\theta)^2 M - 16 \sin(\theta)^4 J^2 - r^4 \sin(\theta)^2} - \frac{16 \cos(\theta) \sin(\theta) J^2}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4}$$

(%i9) /* compute Riemann tensor elements */
for rho:0 thru 3 do {
for sigma:0 thru 3 do {
for mu:0 thru 3 do {
for nu:0 thru 3 do {
R[rho,sigma,mu,nu] :
diff(Gamma[rho,nu,sigma],x[mu]) -
diff(Gamma[rho,mu,sigma],x[nu]) +
/* lambda sums by function call: */
sum(
Gamma[rho,mu,lambda] * Gamma[lambda,nu,sigma] -
Gamma[rho,nu,lambda] * Gamma[lambda,mu,sigma],
lambda, 0, 3)
}}}}\$

(%i10) /* display R's being different from zero */
for i:0 thru 3 do {
for j:0 thru 3 do {
for k:0 thru 3 do {
for l:0 thru 3 do {
R[i,j,k,l] : /*ratsimp*/(factor(R[i,j,k,l])),
if R[i,j,k,l] # 0 then display(R[i,j,k,l])
}}}}\$

$$R_{0,0,0,3} = \frac{4 \sin(\theta)^2 J (2 r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 4 r \sin(\theta)^2 J^2 - 16 r \cos(\theta)^2 J^2)}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)}$$

$$R_{0,0,1,2} = \frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

$$R_{0,0,2,1} = - \frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

$$R_{0,0,3,0} = - \frac{4 \sin(\theta)^2 J (2 r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 4 r \sin(\theta)^2 J^2 - 16 r \cos(\theta)^2 J^2)}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)}$$

$$R_{0,1,0,1} = - (2 (4 r^6 M^3 - 64 r^3 \sin(\theta)^2 J^2 M^2 - 4 r^7 M^2 + 256 \sin(\theta)^4 J^4 M + 56 r^4 \sin(\theta)^2 J^2 M + r^8 M - 96 r \sin(\theta)^4 J^4 - 14 r^5 \sin(\theta)^2 J^2)) / (r^2 (2 M - r) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2)$$

$$\begin{aligned}
R_{0,1,0,2} &= -\frac{16 \cos(\theta) \sin(\theta) J^2 (3 r^3 M - 24 \sin(\theta)^2 J^2 - 2 r^4)}{(r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4))^2} \\
R_{0,1,1,0} &= (2 (4 r^6 M^3 - 64 r^3 \sin(\theta)^2 J^2 M^2 - 4 r^7 M^2 + 256 \sin(\theta)^4 J^4 M + 56 r^4 \sin(\theta)^2 J^2 M + r^8 M - 96 r \sin(\theta)^4 J^4 - 14 r^5 \sin(\theta)^2 J^2)) / (r^2 (2 M - r) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2) \\
R_{0,1,1,3} &= -\frac{6 r \sin(\theta)^2 J (4 r^3 M^2 + 16 \sin(\theta)^2 J^2 M - 4 r^4 M - 16 r \sin(\theta)^2 J^2 + r^5)}{(2 M - r) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{0,1,2,0} &= \frac{16 \cos(\theta) \sin(\theta) J^2 (3 r^3 M - 24 \sin(\theta)^2 J^2 - 2 r^4)}{(r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4))^2} \\
R_{0,1,2,3} &= \frac{12 r^2 \cos(\theta) \sin(\theta) J (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{0,1,3,1} &= \frac{6 r \sin(\theta)^2 J (4 r^3 M^2 + 16 \sin(\theta)^2 J^2 M - 4 r^4 M - 16 r \sin(\theta)^2 J^2 + r^5)}{(2 M - r) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{0,1,3,2} &= -\frac{12 r^2 \cos(\theta) \sin(\theta) J (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{0,2,0,1} &= -\frac{8 \cos(\theta) \sin(\theta) J^2 (12 r^3 M - 48 \sin(\theta)^2 J^2 - 7 r^4)}{(r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4))^2} \\
R_{0,2,0,2} &= - (4 r^6 M^3 - 64 r^3 \sin(\theta)^2 J^2 M^2 - 4 r^7 M^2 + 256 \sin(\theta)^4 J^4 M + 80 r^4 \sin(\theta)^2 J^2 M - 32 r^4 \cos(\theta)^2 J^2 M + r^8 M - 384 r \sin(\theta)^4 J^4 - 24 r^5 \sin(\theta)^2 J^2 + 16 r^5 \cos(\theta)^2 J^2) / (r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2) \\
R_{0,2,1,0} &= \frac{8 \cos(\theta) \sin(\theta) J^2 (12 r^3 M - 48 \sin(\theta)^2 J^2 - 7 r^4)}{(r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4))^2} \\
R_{0,2,1,3} &= \frac{6 r^2 \cos(\theta) \sin(\theta) J}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4} \\
R_{0,2,2,0} &= (4 r^6 M^3 - 64 r^3 \sin(\theta)^2 J^2 M^2 - 4 r^7 M^2 + 256 \sin(\theta)^4 J^4 M + 80 r^4 \sin(\theta)^2 J^2 M - 32 r^4 \cos(\theta)^2 J^2 M + r^8 M - 384 r \sin(\theta)^4 J^4 - 24 r^5 \sin(\theta)^2 J^2 + 16 r^5 \cos(\theta)^2 J^2) / (r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2) \\
R_{0,2,2,3} &= -\frac{6 r^2 \sin(\theta)^2 J (2 M - r)}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4} \\
R_{0,2,3,1} &= -\frac{6 r^2 \cos(\theta) \sin(\theta) J}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4}
\end{aligned}$$

$$\begin{aligned}
R_{0,2,3,2} &= \frac{6 r^2 \sin(\theta)^2 J(2M - r)}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4} \\
R_{0,3,0,3} &= -\frac{\sin(\theta)^2 (2r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 4r \sin(\theta)^2 J^2 - 16r \cos(\theta)^2 J^2)}{r(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{0,3,1,2} &= -\frac{6 r^5 \cos(\theta) \sin(\theta) J(2M - r)}{(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{0,3,2,1} &= \frac{6 r^5 \cos(\theta) \sin(\theta) J(2M - r)}{(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{0,3,3,0} &= \frac{\sin(\theta)^2 (2r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 4r \sin(\theta)^2 J^2 - 16r \cos(\theta)^2 J^2)}{r(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{1,0,0,1} &= - \\
&\frac{2(4r^3 M^3 - 32 \sin(\theta)^2 J^2 M^2 - 4r^4 M^2 + 16r \sin(\theta)^2 J^2 M + r^5 M - 2r^2 \sin(\theta)^2 J^2)}{r^4(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{1,0,0,2} &= \frac{8 \cos(\theta) \sin(\theta) J^2 (2M - r)}{r^2(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{1,0,1,0} &= \\
&\frac{2(4r^3 M^3 - 32 \sin(\theta)^2 J^2 M^2 - 4r^4 M^2 + 16r \sin(\theta)^2 J^2 M + r^5 M - 2r^2 \sin(\theta)^2 J^2)}{r^4(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{1,0,1,3} &= -\frac{2 \sin(\theta)^2 J(8r^3 M^2 - 64 \sin(\theta)^2 J^2 M - 10r^4 M + 24r \sin(\theta)^2 J^2 + 3r^5)}{r^4(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{1,0,2,0} &= -\frac{8 \cos(\theta) \sin(\theta) J^2 (2M - r)}{r^2(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{1,0,2,3} &= \frac{12 \cos(\theta) \sin(\theta) J(2M - r)(2r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^3(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{1,0,3,1} &= \frac{2 \sin(\theta)^2 J(8r^3 M^2 - 64 \sin(\theta)^2 J^2 M - 10r^4 M + 24r \sin(\theta)^2 J^2 + 3r^5)}{r^4(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{1,0,3,2} &= -\frac{12 \cos(\theta) \sin(\theta) J(2M - r)(2r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^3(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{1,2,0,3} &= \frac{6 \cos(\theta) \sin(\theta) J(2M - r)^2}{2r^3 M - 16 \sin(\theta)^2 J^2 - r^4} \\
R_{1,2,1,2} &= -\frac{M}{r} \\
R_{1,2,2,1} &= \frac{M}{r}
\end{aligned}$$

$$\begin{aligned}
R_{1,2,3,0} &= -\frac{6 \cos(\theta) \sin(\theta) J (2M - r)^2}{2r^3 M - 16 \sin(\theta)^2 J^2 - r^4} \\
R_{1,3,0,1} &= \frac{2 \sin(\theta)^2 J (8r^3 M^2 - 64 \sin(\theta)^2 J^2 M - 10r^4 M + 24r \sin(\theta)^2 J^2 + 3r^5)}{r^4 (2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{1,3,0,2} &= -\frac{6 \cos(\theta) \sin(\theta) J (2M - r)}{r^3} \\
R_{1,3,1,0} &= -\frac{2 \sin(\theta)^2 J (8r^3 M^2 - 64 \sin(\theta)^2 J^2 M - 10r^4 M + 24r \sin(\theta)^2 J^2 + 3r^5)}{r^4 (2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{1,3,1,3} &= -\frac{\sin(\theta)^2 (2r^3 M^2 + 56 \sin(\theta)^2 J^2 M - r^4 M - 36r \sin(\theta)^2 J^2)}{r (2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{1,3,2,0} &= \frac{6 \cos(\theta) \sin(\theta) J (2M - r)}{r^3} \\
R_{1,3,3,1} &= \frac{\sin(\theta)^2 (2r^3 M^2 + 56 \sin(\theta)^2 J^2 M - r^4 M - 36r \sin(\theta)^2 J^2)}{r (2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{2,0,0,1} &= -\frac{8 \cos(\theta) \sin(\theta) J^2}{r^3 (2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{2,0,0,2} &= \frac{(2M - r)(2r^3 M^2 - 16 \sin(\theta)^2 J^2 M - r^4 M - 16r \cos(\theta)^2 J^2)}{r^4 (2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{2,0,1,0} &= \frac{8 \cos(\theta) \sin(\theta) J^2}{r^3 (2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{2,0,1,3} &= -\frac{6 \cos(\theta) \sin(\theta) J}{r^4} \\
R_{2,0,2,0} &= -\frac{(2M - r)(2r^3 M^2 - 16 \sin(\theta)^2 J^2 M - r^4 M - 16r \cos(\theta)^2 J^2)}{r^4 (2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{2,0,2,3} &= \frac{2 \sin(\theta)^2 J (2M - 3r)}{r^4} \\
R_{2,0,3,1} &= \frac{6 \cos(\theta) \sin(\theta) J}{r^4} \\
R_{2,0,3,2} &= -\frac{2 \sin(\theta)^2 J (2M - 3r)}{r^4} \\
R_{2,1,0,3} &= \frac{6 \cos(\theta) \sin(\theta) J (2M - r)}{r (2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{2,1,1,2} &= -\frac{M}{r^2 (2M - r)}
\end{aligned}$$

$$\begin{aligned}
R_{2,1,2,1} &= \frac{M}{r^2(2M - r)} \\
R_{2,1,3,0} &= -\frac{6 \cos(\theta) \sin(\theta) J(2M - r)}{r(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{2,3,0,1} &= \frac{12 \cos(\theta) \sin(\theta) J(2r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^4(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{2,3,0,2} &= -\frac{2 \sin(\theta)^2 J(2M - 3r)}{r^4} \\
R_{2,3,1,0} &= -\frac{12 \cos(\theta) \sin(\theta) J(2r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^4(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{2,3,2,0} &= \frac{2 \sin(\theta)^2 J(2M - 3r)}{r^4} \\
R_{2,3,2,3} &= \frac{2 \sin(\theta)^2 M}{r} \\
R_{2,3,3,2} &= -\frac{2 \sin(\theta)^2 M}{r} \\
R_{3,0,0,3} &= \frac{(2M - r)(2r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 4r \sin(\theta)^2 J^2 - 16r \cos(\theta)^2 J^2)}{r^4(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{3,0,1,2} &= \frac{6r^2 \cos(\theta) J(2M - r)^2}{\sin(\theta)(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{3,0,2,1} &= -\frac{6r^2 \cos(\theta) J(2M - r)^2}{\sin(\theta)(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{3,0,3,0} &= -\frac{(2M - r)(2r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 4r \sin(\theta)^2 J^2 - 16r \cos(\theta)^2 J^2)}{r^4(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{3,1,0,1} &= -\frac{2J(12r^3 M^2 - 48 \sin(\theta)^2 J^2 M - 12r^4 M + 16r \sin(\theta)^2 J^2 + 3r^5)}{r(2M - r)(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{3,1,0,2} &= -\frac{2\cos(\theta) J(12r^3 M^2 - 96 \sin(\theta)^2 J^2 M - 12r^4 M + 32r \sin(\theta)^2 J^2 + 3r^5)}{r \sin(\theta)(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{3,1,1,0} &= \frac{2J(12r^3 M^2 - 48 \sin(\theta)^2 J^2 M - 12r^4 M + 16r \sin(\theta)^2 J^2 + 3r^5)}{r(2M - r)(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{3,1,1,3} &= -\frac{(4r^6 M^3 + 176r^3 \sin(\theta)^2 J^2 M^2 - 4r^7 M^2 - 512 \sin(\theta)^4 J^4 M - 208r^4 \sin(\theta)^2 J^2 M + r^8 M + 192r \sin(\theta)^4 J^4 + 60r^5 \sin(\theta)^2 J^2) / (r^2 (2M - r)(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2)}{(2M - r)(2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}
\end{aligned}$$

$$\begin{aligned}
R_{3,1,2,0} &= \frac{2 \cos(\theta) J (12 r^3 M^2 - 96 \sin(\theta)^2 J^2 M - 12 r^4 M + 32 r \sin(\theta)^2 J^2 + 3 r^5)}{r \sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{3,1,2,3} &= \frac{48 \cos(\theta) \sin(\theta) J^2 (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{3,1,3,1} &= (4 r^6 M^3 + 176 r^3 \sin(\theta)^2 J^2 M^2 - 4 r^7 M^2 - 512 \sin(\theta)^4 J^4 M - \\
&\quad 208 r^4 \sin(\theta)^2 J^2 M + r^8 M + 192 r \sin(\theta)^4 J^4 + 60 r^5 \sin(\theta)^2 J^2) / (r^2 \\
&\quad (2 M - r) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2) \\
R_{3,1,3,2} &= -\frac{48 \cos(\theta) \sin(\theta) J^2 (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{3,2,0,1} &= -\frac{4 \cos(\theta) J (12 r^3 M^2 - 48 \sin(\theta)^2 J^2 M - 12 r^4 M + 16 r \sin(\theta)^2 J^2 + 3 r^5)}{r \sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{3,2,0,2} &= -\frac{2 J (2 M - r) (6 r^3 M - 48 \sin(\theta)^2 J^2 - 32 \cos(\theta)^2 J^2 - 3 r^4)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{3,2,1,0} &= \frac{4 \cos(\theta) J (12 r^3 M^2 - 48 \sin(\theta)^2 J^2 M - 12 r^4 M + 16 r \sin(\theta)^2 J^2 + 3 r^5)}{r \sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{3,2,1,3} &= \frac{24 \cos(\theta) \sin(\theta) J^2}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{3,2,2,0} &= \frac{2 J (2 M - r) (6 r^3 M - 48 \sin(\theta)^2 J^2 - 32 \cos(\theta)^2 J^2 - 3 r^4)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{3,2,2,3} &= -\frac{2 (2 r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 12 r \sin(\theta)^2 J^2)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{3,2,3,1} &= -\frac{24 \cos(\theta) \sin(\theta) J^2}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{3,2,3,2} &= \frac{2 (2 r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 12 r \sin(\theta)^2 J^2)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{3,3,0,3} &= -\frac{4 \sin(\theta)^2 J (2 r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 4 r \sin(\theta)^2 J^2 - 16 r \cos(\theta)^2 J^2)}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} \\
R_{3,3,1,2} &= -\frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
R_{3,3,2,1} &= \frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}
\end{aligned}$$

$$R_{3,3,3,0} = \frac{4 \sin(\theta)^2 J (2 r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 4 r \sin(\theta)^2 J^2 - 16 r \cos(\theta)^2 J^2)}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)}$$

(%i11) /* Ricci tensor Ric[mu,nu] */
for mu:0 thru 3 do {
for nu:0 thru 3 do {
Ric[mu,nu]: sum(R[lambda,mu,lambda,nu], lambda, 0, 3)
}}\$

(%i12) /* display Ric's being different from zero */
for i:0 thru 3 do {
for j:0 thru 3 do {
Ric[i,j] : /*ratsimp*/(factor(Ric[i,j])),
if Ric[i,j] # 0 then display(Ric[i,j])
}}\$

$$Ric_{0,0} = -\frac{8 J^2 (6 \sin(\theta)^2 M^2 - 4 r \sin(\theta)^2 M - 8 r \cos(\theta)^2 M + r^2 \sin(\theta)^2 + 4 r^2 \cos(\theta)^2)}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)}$$

$$Ric_{0,3} = \frac{32 \sin(\theta)^2 J^3 (3 \sin(\theta)^2 M + r \sin(\theta)^2 - 2 r \cos(\theta)^2)}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)}$$

$$Ric_{1,1} = \frac{8 \sin(\theta)^2 J^2 (30 r^3 M^2 - 96 \sin(\theta)^2 J^2 M - 36 r^4 M + 48 r \sin(\theta)^2 J^2 + 11 r^5)}{r^2 (2 M - r) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

$$Ric_{1,2} = -\frac{16 \cos(\theta) \sin(\theta) J^2 (9 r^3 M - 48 \sin(\theta)^2 J^2 - 5 r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

$$Ric_{2,1} = -\frac{16 \cos(\theta) \sin(\theta) J^2 (9 r^3 M - 48 \sin(\theta)^2 J^2 - 5 r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

$$Ric_{2,2} = (16 J^2 (6 r^3 \sin(\theta)^2 M^2 - 48 \sin(\theta)^4 J^2 M - 9 r^4 \sin(\theta)^2 M + 2 r^4 \cos(\theta)^2 M + 48 r \sin(\theta)^4 J^2 + 3 r^5 \sin(\theta)^2 - r^5 \cos(\theta)^2)) / (r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2)$$

$$Ric_{3,0} = \frac{32 \sin(\theta)^2 J^3 (3 \sin(\theta)^2 M + r \sin(\theta)^2 - 2 r \cos(\theta)^2)}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)}$$

$$Ric_{3,3} = -\frac{8 \sin(\theta)^2 J^2 (12 \sin(\theta)^2 M - 5 r \sin(\theta)^2 - 2 r \cos(\theta)^2)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)}$$

(%i13) /* Ricci Scalar */
RicSc: sum(gContr[0,lambda]*Ric[lambda,0], lambda, 0, 3)
+ sum(gContr[1,lambda]*Ric[lambda,1], lambda, 0, 3)
+ sum(gContr[2,lambda]*Ric[lambda,2], lambda, 0, 3)
+ sum(gContr[3,lambda]*Ric[lambda,3], lambda, 0, 3);

```
(%o13)  ( 16 J2 ( 6 r3 sin(θ)2 M2 - 48 sin(θ)4 J2 M - 9 r4 sin(θ)2 M + 2 r4
cos(θ)2 M + 48 r sin(θ)4 J2 + 3 r5 sin(θ)2 - r5 cos(θ)2 ) ) / ( r3
(2 r3 M - 16 sin(θ)2 J2 - r4)2 ) -
8 J2 ( 6 sin(θ)2 M2 - 4 r sin(θ)2 M - 8 r cos(θ)2 M + r2 sin(θ)2 + 4 r2 cos(θ)2 )
----- +
( 2 r3 M - 16 sin(θ)2 J2 - r4)2
8 sin(θ)2 J2 ( 30 r3 M2 - 96 sin(θ)2 J2 M - 36 r4 M + 48 r sin(θ)2 J2 + 11 r5 )
----- -
r3 ( 2 r3 M - 16 sin(θ)2 J2 - r4)2
8 sin(θ)2 J2 ( 2 r M - r2 )( 12 sin(θ)2 M - 5 r sin(θ)2 - 2 r cos(θ)2 )
----- +
r ( 2 r3 M - 16 sin(θ)2 J2 - r4 )( 2 r3 sin(θ)2 M - 16 sin(θ)4 J2 - r4 sin(θ)2 )
256 sin(θ)2 J4 ( 3 sin(θ)2 M + r sin(θ)2 - 2 r cos(θ)2 )
----- +
r3 ( 2 r3 M - 16 sin(θ)2 J2 - r4)2

(%i14) ratsimp(RicSc);
(%o14) - ( 384 r3 sin(θ)2 J2 M2 +
((- 352 r4 sin(θ)2 - 128 r4 cos(θ)2) J2 - 768 sin(θ)4 J4 ) M +
(512 r cos(θ)2 sin(θ)2 - 640 r sin(θ)4 ) J4 + (88 r5 sin(θ)2 + 64 r5 cos(θ)2 ) J2 ) / (
4 r9 M2 + (- 64 r6 sin(θ)2 J2 - 4 r10 ) M + 256 r3 sin(θ)4 J4 + 32 r7 sin(θ)2 J2 +
r11 )

(%i15)
/* Test for R^q */
for mu: 0 thru 3 do (
for sigma:0 thru 3 do (
for nu: 0 thru 3 do (
for rho: 0 thru 3 do (
R_q: R[mu,sigma,nu,rho] + R[mu,rho,sigma,nu] + R[mu,nu,rho,sigma],
if R_q # 0 then (
display("=====Einstein equation R^q=0 not fulfilled! "),
display(mu,sigma,nu,rho),
display(R_q)
)
))));;
=====Einstein equation R^q=0 not fulfilled! =
=====Einstein equation R^q=0 not fulfilled!
μ = 0
σ = 0
ν = 1
ρ = 2
```

$$\begin{aligned}
R_q = & - \frac{8 \cos(\theta) \sin(\theta) J^2 (12 r^3 M - 48 \sin(\theta)^2 J^2 - 7 r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} + \\
& \frac{16 \cos(\theta) \sin(\theta) J^2 (3 r^3 M - 24 \sin(\theta)^2 J^2 - 2 r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} + \frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
===== & Einstein\ equation\ R^{\wedge}q=0\ not\ fulfilled! = \\
===== & Einstein\ equation\ R^{\wedge}q=0\ not\ fulfilled! \\
\mu = & 0 \\
\sigma = & 0 \\
\nu = & 2 \\
\rho = & 1 \\
R_q = & \frac{8 \cos(\theta) \sin(\theta) J^2 (12 r^3 M - 48 \sin(\theta)^2 J^2 - 7 r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} - \\
& \frac{16 \cos(\theta) \sin(\theta) J^2 (3 r^3 M - 24 \sin(\theta)^2 J^2 - 2 r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} - \frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
===== & Einstein\ equation\ R^{\wedge}q=0\ not\ fulfilled! = \\
===== & Einstein\ equation\ R^{\wedge}q=0\ not\ fulfilled! \\
\mu = & 0 \\
\sigma = & 1 \\
\nu = & 0 \\
\rho = & 2 \\
R_q = & \frac{8 \cos(\theta) \sin(\theta) J^2 (12 r^3 M - 48 \sin(\theta)^2 J^2 - 7 r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} - \\
& \frac{16 \cos(\theta) \sin(\theta) J^2 (3 r^3 M - 24 \sin(\theta)^2 J^2 - 2 r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} - \frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} \\
===== & Einstein\ equation\ R^{\wedge}q=0\ not\ fulfilled! = \\
===== & Einstein\ equation\ R^{\wedge}q=0\ not\ fulfilled! \\
\mu = & 0 \\
\sigma = & 1 \\
\nu = & 2 \\
\rho = & 0 \\
R_q = & - \frac{8 \cos(\theta) \sin(\theta) J^2 (12 r^3 M - 48 \sin(\theta)^2 J^2 - 7 r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} + \\
& \frac{16 \cos(\theta) \sin(\theta) J^2 (3 r^3 M - 24 \sin(\theta)^2 J^2 - 2 r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} + \frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}
\end{aligned}$$

=====Einstein equation $R^{\wedge}q=0$ not fulfilled! =

=====Einstein equation $R^{\wedge}q=0$ not fulfilled!

$\mu = 0$

$\sigma = 1$

$\nu = 2$

$\rho = 3$

$$R_q = \frac{12 r^2 \cos(\theta) \sin(\theta) J (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} - \frac{6 r^2 \cos(\theta) \sin(\theta) J}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4} - \frac{6 r^5 \cos(\theta) \sin(\theta) J (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

=====Einstein equation $R^{\wedge}q=0$ not fulfilled! =

=====Einstein equation $R^{\wedge}q=0$ not fulfilled!

$\mu = 0$

$\sigma = 1$

$\nu = 3$

$\rho = 2$

$$R_q = - \frac{12 r^2 \cos(\theta) \sin(\theta) J (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} + \frac{6 r^2 \cos(\theta) \sin(\theta) J}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4} + \frac{6 r^5 \cos(\theta) \sin(\theta) J (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

=====Einstein equation $R^{\wedge}q=0$ not fulfilled! =

=====Einstein equation $R^{\wedge}q=0$ not fulfilled!

$\mu = 0$

$\sigma = 2$

$\nu = 0$

$\rho = 1$

$$R_q = - \frac{8 \cos(\theta) \sin(\theta) J^2 (12 r^3 M - 48 \sin(\theta)^2 J^2 - 7 r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} + \frac{16 \cos(\theta) \sin(\theta) J^2 (3 r^3 M - 24 \sin(\theta)^2 J^2 - 2 r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} + \frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

=====Einstein equation $R^{\wedge}q=0$ not fulfilled! =

=====Einstein equation $R^{\wedge}q=0$ not fulfilled!

$\mu = 0$

$\sigma = 2$

$\nu = 1$

$\rho = 0$

$$R_Q = \frac{8 \cos(\theta) \sin(\theta) J^2 (12 r^3 M - 48 \sin(\theta)^2 J^2 - 7 r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} - \frac{16 \cos(\theta) \sin(\theta) J^2 (3 r^3 M - 24 \sin(\theta)^2 J^2 - 2 r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} - \frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

===== Einstein equation $R^{\wedge}q=0$ not fulfilled! =

===== Einstein equation $R^{\wedge}q=0$ not fulfilled!

$\mu = 0$

$\sigma = 2$

$\nu = 1$

$\rho = 3$

$$R_Q = -\frac{12 r^2 \cos(\theta) \sin(\theta) J (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} + \frac{6 r^2 \cos(\theta) \sin(\theta) J}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4} + \frac{6 r^5 \cos(\theta) \sin(\theta) J (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

===== Einstein equation $R^{\wedge}q=0$ not fulfilled! =

===== Einstein equation $R^{\wedge}q=0$ not fulfilled!

$\mu = 0$

$\sigma = 2$

$\nu = 3$

$\rho = 1$

$$R_Q = \frac{12 r^2 \cos(\theta) \sin(\theta) J (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} - \frac{6 r^2 \cos(\theta) \sin(\theta) J}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4} - \frac{6 r^5 \cos(\theta) \sin(\theta) J (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

===== Einstein equation $R^{\wedge}q=0$ not fulfilled! =

===== Einstein equation $R^{\wedge}q=0$ not fulfilled!

$\mu = 0$

$\sigma = 3$

$\nu = 1$

$\rho = 2$

$$R_Q = \frac{12 r^2 \cos(\theta) \sin(\theta) J (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} - \frac{6 r^2 \cos(\theta) \sin(\theta) J}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4} -$$

$$\frac{6 r^5 \cos(\theta) \sin(\theta) J(2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

=====Einstein equation $R^{\hat{q}}=0$ not fulfilled! =

=====Einstein equation $R^{\hat{q}}=0$ not fulfilled!

$\mu = 0$

$\sigma = 3$

$\nu = 2$

$\rho = 1$

$$R_q = -\frac{12 r^2 \cos(\theta) \sin(\theta) J(2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} + \frac{6 r^2 \cos(\theta) \sin(\theta) J}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4} +$$

$$\frac{6 r^5 \cos(\theta) \sin(\theta) J(2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

=====Einstein equation $R^{\hat{q}}=0$ not fulfilled! =

=====Einstein equation $R^{\hat{q}}=0$ not fulfilled!

$\mu = 1$

$\sigma = 0$

$\nu = 2$

$\rho = 3$

$$R_q = \frac{12 \cos(\theta) \sin(\theta) J(2 M - r)(2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^3 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} - \frac{6 \cos(\theta) \sin(\theta) J(2 M - r)^2}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4} -$$

$$\frac{6 \cos(\theta) \sin(\theta) J(2 M - r)}{r^3}$$

=====Einstein equation $R^{\hat{q}}=0$ not fulfilled! =

=====Einstein equation $R^{\hat{q}}=0$ not fulfilled!

$\mu = 1$

$\sigma = 0$

$\nu = 3$

$\rho = 2$

$$R_q = -\frac{12 \cos(\theta) \sin(\theta) J(2 M - r)(2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^3 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} + \frac{6 \cos(\theta) \sin(\theta) J(2 M - r)^2}{2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4} +$$

$$\frac{6 \cos(\theta) \sin(\theta) J(2 M - r)}{r^3}$$

=====Einstein equation $R^{\hat{q}}=0$ not fulfilled! =

=====Einstein equation $R^{\hat{q}}=0$ not fulfilled!

$\mu = 1$

$\sigma = 2$

$v = 0$ $\rho = 3$

$$R_q = -\frac{12 \cos(\theta) \sin(\theta) J(2M - r)(2r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^3 (2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} + \frac{6 \cos(\theta) \sin(\theta) J(2M - r)^2}{2r^3 M - 16 \sin(\theta)^2 J^2 - r^4} +$$

$$\frac{6 \cos(\theta) \sin(\theta) J(2M - r)}{r^3}$$

===== Einstein equation $R^q=0$ not fulfilled! =

===== Einstein equation $R^q=0$ not fulfilled!

 $\mu = 1$ $\sigma = 2$ $\nu = 3$ $\rho = 0$

$$R_q = \frac{12 \cos(\theta) \sin(\theta) J(2M - r)(2r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^3 (2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} - \frac{6 \cos(\theta) \sin(\theta) J(2M - r)^2}{2r^3 M - 16 \sin(\theta)^2 J^2 - r^4} -$$

$$\frac{6 \cos(\theta) \sin(\theta) J(2M - r)}{r^3}$$

===== Einstein equation $R^q=0$ not fulfilled! =

===== Einstein equation $R^q=0$ not fulfilled!

 $\mu = 1$ $\sigma = 3$ $\nu = 0$ $\rho = 2$

$$R_q = \frac{12 \cos(\theta) \sin(\theta) J(2M - r)(2r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^3 (2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} - \frac{6 \cos(\theta) \sin(\theta) J(2M - r)^2}{2r^3 M - 16 \sin(\theta)^2 J^2 - r^4} -$$

$$\frac{6 \cos(\theta) \sin(\theta) J(2M - r)}{r^3}$$

===== Einstein equation $R^q=0$ not fulfilled! =

===== Einstein equation $R^q=0$ not fulfilled!

 $\mu = 1$ $\sigma = 3$ $\nu = 2$ $\rho = 0$

$$R_q = -\frac{12 \cos(\theta) \sin(\theta) J(2M - r)(2r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^3 (2r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} + \frac{6 \cos(\theta) \sin(\theta) J(2M - r)^2}{2r^3 M - 16 \sin(\theta)^2 J^2 - r^4} +$$

$$\frac{6 \cos(\theta) \sin(\theta) J(2M - r)}{r^3}$$

===== Einstein equation $R^q=0$ not fulfilled! =

=====Einstein equation $R^{\wedge}q=0$ not fulfilled!

$\mu = 2$

$\sigma = 0$

$\nu = 1$

$\rho = 3$

$$R_q = \frac{12 \cos(\theta) \sin(\theta) J (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} - \frac{6 \cos(\theta) \sin(\theta) J (2 M - r)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} -$$

$$\frac{6 \cos(\theta) \sin(\theta) J}{r^4}$$

=====Einstein equation $R^{\wedge}q=0$ not fulfilled! =

=====Einstein equation $R^{\wedge}q=0$ not fulfilled!

$\mu = 2$

$\sigma = 0$

$\nu = 3$

$\rho = 1$

$$R_q = - \frac{12 \cos(\theta) \sin(\theta) J (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} + \frac{6 \cos(\theta) \sin(\theta) J (2 M - r)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} +$$

$$\frac{6 \cos(\theta) \sin(\theta) J}{r^4}$$

=====Einstein equation $R^{\wedge}q=0$ not fulfilled! =

=====Einstein equation $R^{\wedge}q=0$ not fulfilled!

$\mu = 2$

$\sigma = 1$

$\nu = 0$

$\rho = 3$

$$R_q = - \frac{12 \cos(\theta) \sin(\theta) J (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} + \frac{6 \cos(\theta) \sin(\theta) J (2 M - r)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} +$$

$$\frac{6 \cos(\theta) \sin(\theta) J}{r^4}$$

=====Einstein equation $R^{\wedge}q=0$ not fulfilled! =

=====Einstein equation $R^{\wedge}q=0$ not fulfilled!

$\mu = 2$

$\sigma = 1$

$\nu = 3$

$\rho = 0$

$$R_q = \frac{12 \cos(\theta) \sin(\theta) J (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} - \frac{6 \cos(\theta) \sin(\theta) J (2 M - r)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} -$$

$$\frac{6 \cos(\theta) \sin(\theta) J}{r^4}$$

===== Einstein equation $R^{\hat{q}=0}$ not fulfilled! =

===== Einstein equation $R^{\hat{q}=0}$ not fulfilled!

$\mu = 2$

$\sigma = 3$

$\nu = 0$

$\rho = 1$

$$R_{\hat{q}} = \frac{12 \cos(\theta) \sin(\theta) J (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} - \frac{6 \cos(\theta) \sin(\theta) J (2 M - r)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} -$$

$$\frac{6 \cos(\theta) \sin(\theta) J}{r^4}$$

===== Einstein equation $R^{\hat{q}=0}$ not fulfilled! =

===== Einstein equation $R^{\hat{q}=0}$ not fulfilled!

$\mu = 2$

$\sigma = 3$

$\nu = 1$

$\rho = 0$

$$R_{\hat{q}} = - \frac{12 \cos(\theta) \sin(\theta) J (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} + \frac{6 \cos(\theta) \sin(\theta) J (2 M - r)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} +$$

$$\frac{6 \cos(\theta) \sin(\theta) J}{r^4}$$

===== Einstein equation $R^{\hat{q}=0}$ not fulfilled! =

===== Einstein equation $R^{\hat{q}=0}$ not fulfilled!

$\mu = 3$

$\sigma = 0$

$\nu = 1$

$\rho = 2$

$$R_{\hat{q}} = - \frac{4 \cos(\theta) J (12 r^3 M^2 - 48 \sin(\theta)^2 J^2 M - 12 r^4 M + 16 r \sin(\theta)^2 J^2 + 3 r^5)}{r \sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} +$$

$$\frac{2 \cos(\theta) J (12 r^3 M^2 - 96 \sin(\theta)^2 J^2 M - 12 r^4 M + 32 r \sin(\theta)^2 J^2 + 3 r^5)}{r \sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} +$$

$$\frac{6 r^2 \cos(\theta) J (2 M - r)^2}{\sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

===== Einstein equation $R^{\hat{q}=0}$ not fulfilled! =

===== Einstein equation $R^{\hat{q}=0}$ not fulfilled!

$\mu = 3$ $\sigma = 0$ $\nu = 2$ $\rho = 1$

$$R_q = \frac{4 \cos(\theta) J (12 r^3 M^2 - 48 \sin(\theta)^2 J^2 M - 12 r^4 M + 16 r \sin(\theta)^2 J^2 + 3 r^5)}{r \sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} -$$

$$\frac{2 \cos(\theta) J (12 r^3 M^2 - 96 \sin(\theta)^2 J^2 M - 12 r^4 M + 32 r \sin(\theta)^2 J^2 + 3 r^5)}{r \sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} -$$

$$\frac{6 r^2 \cos(\theta) J (2 M - r)^2}{\sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

===== Einstein equation $R^{\hat{q}}=0$ not fulfilled! =

===== Einstein equation $R^{\hat{q}}=0$ not fulfilled!

 $\mu = 3$ $\sigma = 1$ $\nu = 0$ $\rho = 2$

$$R_q = \frac{4 \cos(\theta) J (12 r^3 M^2 - 48 \sin(\theta)^2 J^2 M - 12 r^4 M + 16 r \sin(\theta)^2 J^2 + 3 r^5)}{r \sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} -$$

$$\frac{2 \cos(\theta) J (12 r^3 M^2 - 96 \sin(\theta)^2 J^2 M - 12 r^4 M + 32 r \sin(\theta)^2 J^2 + 3 r^5)}{r \sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} -$$

$$\frac{6 r^2 \cos(\theta) J (2 M - r)^2}{\sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

===== Einstein equation $R^{\hat{q}}=0$ not fulfilled! =

===== Einstein equation $R^{\hat{q}}=0$ not fulfilled!

 $\mu = 3$ $\sigma = 1$ $\nu = 2$ $\rho = 0$

$$R_q = - \frac{4 \cos(\theta) J (12 r^3 M^2 - 48 \sin(\theta)^2 J^2 M - 12 r^4 M + 16 r \sin(\theta)^2 J^2 + 3 r^5)}{r \sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} +$$

$$\frac{2 \cos(\theta) J (12 r^3 M^2 - 96 \sin(\theta)^2 J^2 M - 12 r^4 M + 32 r \sin(\theta)^2 J^2 + 3 r^5)}{r \sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} +$$

$$\frac{6 r^2 \cos(\theta) J (2 M - r)^2}{\sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

$$\frac{6 r^2 \cos(\theta) J (2 M - r)^2}{\sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

=====Einstein equation $R^{\wedge}q=0$ not fulfilled! =

=====Einstein equation $R^{\wedge}q=0$ not fulfilled!

$\mu = 3$

$\sigma = 1$

$\nu = 2$

$\rho = 3$

$$R_q = \frac{\frac{48 \cos(\theta) \sin(\theta) J^2 (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} - \frac{24 \cos(\theta) \sin(\theta) J^2}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} - \frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}}$$

=====Einstein equation $R^{\wedge}q=0$ not fulfilled! =

=====Einstein equation $R^{\wedge}q=0$ not fulfilled!

$\mu = 3$

$\sigma = 1$

$\nu = 3$

$\rho = 2$

$$R_q = -\frac{\frac{48 \cos(\theta) \sin(\theta) J^2 (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} + \frac{24 \cos(\theta) \sin(\theta) J^2}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} + \frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}}$$

$$\frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

=====Einstein equation $R^{\wedge}q=0$ not fulfilled! =

=====Einstein equation $R^{\wedge}q=0$ not fulfilled!

$\mu = 3$

$\sigma = 2$

$\nu = 0$

$\rho = 1$

$$R_q = -\frac{\frac{4 \cos(\theta) J (12 r^3 M^2 - 48 \sin(\theta)^2 J^2 M - 12 r^4 M + 16 r \sin(\theta)^2 J^2 + 3 r^5)}{r \sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} + \frac{2 \cos(\theta) J (12 r^3 M^2 - 96 \sin(\theta)^2 J^2 M - 12 r^4 M + 32 r \sin(\theta)^2 J^2 + 3 r^5)}{r \sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}}$$

$$\frac{6 r^2 \cos(\theta) J (2 M - r)^2}{\sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

=====Einstein equation $R^{\wedge}q=0$ not fulfilled! =

=====Einstein equation $R^{\wedge}q=0$ not fulfilled!

$\mu = 3$

$\sigma = 2$ $\nu = 1$ $\rho = 0$

$$R_q = \frac{4 \cos(\theta) J (12 r^3 M^2 - 48 \sin(\theta)^2 J^2 M - 12 r^4 M + 16 r \sin(\theta)^2 J^2 + 3 r^5)}{r \sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} -$$

$$\frac{2 \cos(\theta) J (12 r^3 M^2 - 96 \sin(\theta)^2 J^2 M - 12 r^4 M + 32 r \sin(\theta)^2 J^2 + 3 r^5)}{r \sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} -$$

$$\frac{6 r^2 \cos(\theta) J (2 M - r)^2}{\sin(\theta) (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

===== Einstein equation $R^q=0$ not fulfilled! =

===== Einstein equation $R^q=0$ not fulfilled!

 $\mu = 3$ $\sigma = 2$ $\nu = 1$ $\rho = 3$

$$R_q = - \frac{48 \cos(\theta) \sin(\theta) J^2 (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} + \frac{24 \cos(\theta) \sin(\theta) J^2}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} +$$

$$\frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

===== Einstein equation $R^q=0$ not fulfilled! =

===== Einstein equation $R^q=0$ not fulfilled!

 $\mu = 3$ $\sigma = 2$ $\nu = 3$ $\rho = 1$

$$R_q = \frac{48 \cos(\theta) \sin(\theta) J^2 (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} - \frac{24 \cos(\theta) \sin(\theta) J^2}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} -$$

$$\frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

===== Einstein equation $R^q=0$ not fulfilled! =

===== Einstein equation $R^q=0$ not fulfilled!

 $\mu = 3$ $\sigma = 3$ $\nu = 1$ $\rho = 2$

$R_Q = \frac{48 \cos(\theta) \sin(\theta) J^2 (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} - \frac{24 \cos(\theta) \sin(\theta) J^2}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} -$

 $\frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$

===== Einstein equation $R^Q=0$ not fulfilled! =

===== Einstein equation $R^Q=0$ not fulfilled!

$\mu = 3$

$\sigma = 3$

$\nu = 2$

$\rho = 1$

$R_Q = - \frac{48 \cos(\theta) \sin(\theta) J^2 (2 r^3 M - 8 \sin(\theta)^2 J^2 - r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} + \frac{24 \cos(\theta) \sin(\theta) J^2}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)} +$

 $\frac{24 r^2 \cos(\theta) \sin(\theta) J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$

(%o15) done

(%i16) /* Raising of indices,
contravarinat metric el. is $g^x x^x$ (contr.) = $1/g_x x^x$ (cov.) */
/*print("Riemann elements R^0_0 , R^0_1 , R^0_2 , R^0_3 :");*/

$R0101: f(0,1);$
 $R0202: f(0,2);$
 $R0303: f(0,3);$

(%o16) $(2 r (4 r^6 M^3 - 64 r^3 \sin(\theta)^2 J^2 M^2 - 4 r^7 M^2 + 256 \sin(\theta)^4 J^4 M + 56 r^4 \sin(\theta)^2 J^2 M + r^8 M - 96 r \sin(\theta)^4 J^4 - 14 r^5 \sin(\theta)^2 J^2)) / (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^3 -$

 $\frac{24 r \sin(\theta)^2 J^2 (4 r^3 M^2 + 16 \sin(\theta)^2 J^2 M - 4 r^4 M - 16 r \sin(\theta)^2 J^2 + r^5)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^3}$

(%o17) $\frac{24 r \sin(\theta)^2 J^2 (2 M - r)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} - (r (4 r^6 M^3 - 64 r^3 \sin(\theta)^2 J^2 M^2 - 4 r^7 M^2 + 256 \sin(\theta)^4 J^4 M + 80 r^4 \sin(\theta)^2 J^2 M - 32 r^4 \cos(\theta)^2 J^2 M + r^8 M - 384 r \sin(\theta)^4 J^4 - 24 r^5 \sin(\theta)^2 J^2 + 16 r^5 \cos(\theta)^2 J^2)) / (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^3$

(%o18) $\frac{16 r \sin(\theta)^2 J^2 (2 r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 4 r \sin(\theta)^2 J^2 - 16 r \cos(\theta)^2 J^2)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^3} -$

$r^3 \sin(\theta)^2 (2 r M - r^2) (2 r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 4 r \sin(\theta)^2 J^2 - 16 r \cos(\theta)^2 J^2)$

(%i19) R0101: factor(R0101);
R0202: factor(R0202);
R0303: factor(R0303);

(%o19) $\frac{(2 r (4 r^6 M^3 - 112 r^3 \sin(\theta)^2 J^2 M^2 - 4 r^7 M^2 + 64 \sin(\theta)^4 J^4 M + 104 r^4 \sin(\theta)^2 J^2 M + r^8 M + 96 r \sin(\theta)^4 J^4 - 26 r^5 \sin(\theta)^2 J^2))}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^3}$

(%o20) $\frac{-(r (4 r^6 M^3 - 160 r^3 \sin(\theta)^2 J^2 M^2 - 4 r^7 M^2 + 1024 \sin(\theta)^4 J^4 M + 176 r^4 \sin(\theta)^2 J^2 M - 32 r^4 \cos(\theta)^2 J^2 M + r^8 M - 768 r \sin(\theta)^4 J^4 - 48 r^5 \sin(\theta)^2 J^2 + 16 r^5 \cos(\theta)^2 J^2))}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^3}$

(%o21) $\frac{-r (2 r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 4 r \sin(\theta)^2 J^2 - 16 r \cos(\theta)^2 J^2)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$

(%i22) R1010: f(1,0);
R1212: f(1,2);
R1313: f(1,3);

(%o22) $\frac{8 \sin(\theta)^2 J^2 (2 M - r) (8 r^3 M^2 - 64 \sin(\theta)^2 J^2 M - 10 r^4 M + 24 r \sin(\theta)^2 J^2 + 3 r^5)}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} -$

$\frac{2 (2 M - r) (4 r^3 M^3 - 32 \sin(\theta)^2 J^2 M^2 - 4 r^4 M^2 + 16 r \sin(\theta)^2 J^2 M + r^5 M - 2 r^2 \sin(\theta)^2 J^2)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$

(%o23) $\frac{M (2 M - r)}{r^4}$

(%o24) $\frac{8 \sin(\theta)^2 J^2 (2 M - r) (8 r^3 M^2 - 64 \sin(\theta)^2 J^2 M - 10 r^4 M + 24 r \sin(\theta)^2 J^2 + 3 r^5)}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2} +$

$\frac{\sin(\theta)^2 (2 M - r) (2 r M - r^2) (2 r^3 M^2 + 56 \sin(\theta)^2 J^2 M - r^4 M - 36 r \sin(\theta)^2 J^2)}{r^2 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4) (2 r^3 \sin(\theta)^2 M - 16 \sin(\theta)^4 J^2 - r^4 \sin(\theta)^2)}$

(%i25) R1010: factor(R1010);
R1212: factor(R1212);
R1313: factor(R1313);

(%o25) $\frac{-(2 (2 M - r) (4 r^6 M^3 - 64 r^3 \sin(\theta)^2 J^2 M^2 - 4 r^7 M^2 + 256 \sin(\theta)^4 J^4 M + 56 r^4 \sin(\theta)^2 J^2 M + r^8 M - 96 r \sin(\theta)^4 J^4 - 14 r^5 \sin(\theta)^2 J^2))}{r^4 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$

(%o26)
$$\frac{M(2M - r)}{r^4}$$

(%o27)
$$\frac{((2M - r) (4r^6M^3 + 176r^3\sin(\theta)^2J^2M^2 - 4r^7M^2 - 512\sin(\theta)^4J^4M - 208r^4\sin(\theta)^2J^2M + r^8M + 192r\sin(\theta)^4J^4 + 60r^5\sin(\theta)^2J^2)) / (r^4(2r^3M - 16\sin(\theta)^2J^2 - r^4)^2)}$$

(%i28) R2020: f(2,0);
R2121: f(2,1);
R2323: f(2,3);

(%o28)
$$\frac{8\sin(\theta)^2J^2(2M - 3r)}{r^5(2r^3M - 16\sin(\theta)^2J^2 - r^4)} - \frac{(2M - r)(2r^3M^2 - 16\sin(\theta)^2J^2M - r^4M - 16r\cos(\theta)^2J^2)}{r^2(2r^3M - 16\sin(\theta)^2J^2 - r^4)^2}$$

(%o29)
$$-\frac{M}{r^5}$$

(%o30)
$$\frac{2\sin(\theta)^2M(2rM - r^2)}{r^3(2r^3\sin(\theta)^2M - 16\sin(\theta)^4J^2 - r^4\sin(\theta)^2)} + \frac{8\sin(\theta)^2J^2(2M - 3r)}{r^5(2r^3M - 16\sin(\theta)^2J^2 - r^4)}$$

(%i31) R2020: factor(R2020);
R2121: factor(R2121);
R2323: factor(R2323);

(%o31)
$$-\frac{(4r^6M^3 - 64r^3\sin(\theta)^2J^2M^2 - 4r^7M^2 + 256\sin(\theta)^4J^4M + 80r^4\sin(\theta)^2J^2M - 32r^4\cos(\theta)^2J^2M + r^8M - 384r\sin(\theta)^4J^4 - 24r^5\sin(\theta)^2J^2 + 16r^5\cos(\theta)^2J^2)}{(r^5(2r^3M - 16\sin(\theta)^2J^2 - r^4)^2)}$$

(%o32)
$$-\frac{M}{r^5}$$

(%o33)
$$\frac{2(2r^3M^2 + 8\sin(\theta)^2J^2M - r^4M - 12r\sin(\theta)^2J^2)}{r^5(2r^3M - 16\sin(\theta)^2J^2 - r^4)}$$

(%i34) R3030: f(3,0);
R3131: f(3,1);
R3232: f(3,2);

(%o34)
$$\frac{16J^2(2M - r)(2r^3M^2 + 8\sin(\theta)^2J^2M - r^4M - 4r\sin(\theta)^2J^2 - 16r\cos(\theta)^2J^2)}{r^2(2r^3M - 16\sin(\theta)^2J^2 - r^4)^3} - \frac{(2M - r)(2rM - r^2)(2r^3M^2 + 8\sin(\theta)^2J^2M - r^4M - 4r\sin(\theta)^2J^2 - 16r\cos(\theta)^2J^2)}{(2r^3M - 16\sin(\theta)^2J^2 - r^4)^2(2r^3\sin(\theta)^2M - 16\sin(\theta)^4J^2 - r^4\sin(\theta)^2)}$$

(%o35)
$$\frac{8 J^2 (12 r^3 M^2 - 48 \sin(\theta)^2 J^2 M - 12 r^4 M + 16 r \sin(\theta)^2 J^2 + 3 r^5)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^3} - ((2 r M - r^2) (4 r^6 M^3 + 176 r^3 \sin(\theta)^2 J^2 M^2 - 4 r^7 M^2 - 512 \sin(\theta)^4 J^4 M - 208 r^4 \sin(\theta)^2 J^2 M + r^8 M + 192 r \sin(\theta)^4 J^4 + 60 r^5 \sin(\theta)^2 J^2)) / (r^3 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2 (2 r^3 \sin(\theta)^2 M - 16 \sin(\theta)^4 J^2 - r^4 \sin(\theta)^2))$$

(%o36)
$$\frac{2 (2 r M - r^2) (2 r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 12 r \sin(\theta)^2 J^2)}{r^3 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4) (2 r^3 \sin(\theta)^2 M - 16 \sin(\theta)^4 J^2 - r^4 \sin(\theta)^2)} - \frac{8 J^2 (2 M - r) (6 r^3 M - 48 \sin(\theta)^2 J^2 - 32 \cos(\theta)^2 J^2 - 3 r^4)}{r (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^3}$$

(%i37) R3030: factor(R3030);
R3131: factor(R3131);
R3232: factor(R3232);

(%o37)
$$-\frac{(2 M - r) (2 r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 4 r \sin(\theta)^2 J^2 - 16 r \cos(\theta)^2 J^2)}{r^2 \sin(\theta)^2 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

(%o38)
$$- (8 r^6 M^4 + 352 r^3 \sin(\theta)^2 J^2 M^3 - 12 r^7 M^3 - 1024 \sin(\theta)^4 J^4 M^2 - 688 r^4 \sin(\theta)^2 J^2 M^2 + 6 r^8 M^2 + 1280 r \sin(\theta)^4 J^4 M + 424 r^5 \sin(\theta)^2 J^2 M - r^9 M - 320 r^2 \sin(\theta)^4 J^4 - 84 r^6 \sin(\theta)^2 J^2) / (r^2 \sin(\theta)^2 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^3)$$

(%o39)
$$(2 (2 M - r) (4 r^6 M^3 - 16 r^3 \sin(\theta)^2 J^2 M^2 - 4 r^7 M^2 - 128 \sin(\theta)^4 J^4 M - 40 r^4 \sin(\theta)^2 J^2 M + r^8 M + 384 r \sin(\theta)^4 J^4 + 128 r \cos(\theta)^2 \sin(\theta)^2 J^4 + 24 r^5 \sin(\theta)^2 J^2)) / (r^2 \sin(\theta)^2 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^3)$$

(%i40) /* Coulomb law */
DivE : R0101 + R0202 + R0303;

(%o40)
$$(2 r (4 r^6 M^3 - 112 r^3 \sin(\theta)^2 J^2 M^2 - 4 r^7 M^2 + 64 \sin(\theta)^4 J^4 M + 104 r^4 \sin(\theta)^2 J^2 M + r^8 M + 96 r \sin(\theta)^4 J^4 - 26 r^5 \sin(\theta)^2 J^2)) / (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^3 - (r (4 r^6 M^3 - 160 r^3 \sin(\theta)^2 J^2 M^2 - 4 r^7 M^2 + 1024 \sin(\theta)^4 J^4 M + 176 r^4 \sin(\theta)^2 J^2 M - 32 r^4 \cos(\theta)^2 J^2 M + r^8 M - 768 r \sin(\theta)^4 J^4 - 48 r^5 \sin(\theta)^2 J^2 + 16 r^5 \cos(\theta)^2 J^2)) / (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^3 - \frac{r (2 r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 4 r \sin(\theta)^2 J^2 - 16 r \cos(\theta)^2 J^2)}{(2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$

```
(%i41) ratsimp(DivE);
(%o41) - ( 48 r4 sin( $\theta$ )2 J2 M2 +
(768 r sin( $\theta$ )4 J4 + (- 32 r5 sin( $\theta$ )2 - 64 r5 cos( $\theta$ )2) J2 ) M +
(256 r2 cos( $\theta$ )2 sin( $\theta$ )2 - 896 r2 sin( $\theta$ )4) J4 + (8 r6 sin( $\theta$ )2 + 32 r6 cos( $\theta$ )2) J2 ) /
( 8 r9 M3 + (- 192 r6 sin( $\theta$ )2 J2 - 12 r10 ) M2 +
(1536 r3 sin( $\theta$ )4 J4 + 192 r7 sin( $\theta$ )2 J2 + 6 r11 ) M - 4096 sin( $\theta$ )6 J6 - 768 r4
sin( $\theta$ )4 J4 - 48 r8 sin( $\theta$ )2 J2 - r12 )

(%i42) /* J[r] */
Jr : -(R1010 + R1212 + R1313);

(%o42) - ( (2 M - r) ( 4 r6 M3 + 176 r3 sin( $\theta$ )2 J2 M2 - 4 r7 M2 - 512 sin( $\theta$ )4
J4 M - 208 r4 sin( $\theta$ )2 J2 M + r8 M + 192 r sin( $\theta$ )4 J4 + 60 r5 sin( $\theta$ )2 J2 ) ) /
( r4 (2 r3 M - 16 sin( $\theta$ )2 J2 - r4)2 ) + ( 2 (2 M - r) ( 4 r6 M3 - 64 r3 sin( $\theta$ )2 J2
M2 - 4 r7 M2 + 256 sin( $\theta$ )4 J4 M + 56 r4 sin( $\theta$ )2 J2 M + r8 M - 96 r sin( $\theta$ )4 J4
- 14 r5 sin( $\theta$ )2 J2 ) ) / ( r4 (2 r3 M - 16 sin( $\theta$ )2 J2 - r4)2 ) -  $\frac{M(2M-r)}{r^4}$ 

(%i43) ratsimp(Jr);

(%o43) - ( 480 r3 sin( $\theta$ )2 J2 M3 + (- 1536 sin( $\theta$ )4 J4 - 816 r4 sin( $\theta$ )2 J2 ) M2 +
(1536 r sin( $\theta$ )4 J4 + 464 r5 sin( $\theta$ )2 J2 ) M - 384 r2 sin( $\theta$ )4 J4 - 88 r6 sin( $\theta$ )2 J2
) / ( 4 r10 M2 + (- 64 r7 sin( $\theta$ )2 J2 - 4 r11 ) M + 256 r4 sin( $\theta$ )4 J4 + 32 r8
sin( $\theta$ )2 J2 + r12 )

(%i44) /* J[theta] */
Jtheta : -(R2020 + R2121 + R2323);

(%o44) ( 4 r6 M3 - 64 r3 sin( $\theta$ )2 J2 M2 - 4 r7 M2 + 256 sin( $\theta$ )4 J4 M + 80 r4
sin( $\theta$ )2 J2 M - 32 r4 cos( $\theta$ )2 J2 M + r8 M - 384 r sin( $\theta$ )4 J4 - 24 r5 sin( $\theta$ )2
J2 + 16 r5 cos( $\theta$ )2 J2 ) / ( r5 (2 r3 M - 16 sin( $\theta$ )2 J2 - r4)2 ) -
 $\frac{2(2r^3M^2+8\sin(\theta)^2J^2M-r^4M-12r\sin(\theta)^2J^2)}{r^5(2r^3M-16\sin(\theta)^2J^2-r^4)} + \frac{M}{r^5}$ 

(%i45) ratsimp(Jtheta);

(%o45) - ( 96 r3 sin( $\theta$ )2 J2 M2 +
((32 r4 cos( $\theta$ )2 - 144 r4 sin( $\theta$ )2) J2 - 768 sin( $\theta$ )4 J4 ) M + 768 r sin( $\theta$ )4 J4 +
(48 r5 sin( $\theta$ )2 - 16 r5 cos( $\theta$ )2) J2 ) / ( 4 r11 M2 + (- 64 r8 sin( $\theta$ )2 J2 - 4 r12 ) M +
```

```

256  $r^5 \sin(\theta)^4 J^4 + 32 r^9 \sin(\theta)^2 J^2 + r^{13}$  )

(%i46) /* J[phi] */
Jphi : -(R3030 + R3131 + R3232);

(%o46) 
$$\frac{(8 r^6 M^4 + 352 r^3 \sin(\theta)^2 J^2 M^3 - 12 r^7 M^3 - 1024 \sin(\theta)^4 J^4 M^2 - 688 r^4 \sin(\theta)^2 J^2 M^2 + 6 r^8 M^2 + 1280 r \sin(\theta)^4 J^4 M + 424 r^5 \sin(\theta)^2 J^2 M - r^9 M - 320 r^2 \sin(\theta)^4 J^4 - 84 r^6 \sin(\theta)^2 J^2) / (r^2 \sin(\theta)^2 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^3) - (2 (2 M - r) (4 r^6 M^3 - 16 r^3 \sin(\theta)^2 J^2 M^2 - 4 r^7 M^2 - 128 \sin(\theta)^4 J^4 M - 40 r^4 \sin(\theta)^2 J^2 M + r^8 M + 384 r \sin(\theta)^4 J^4 + 128 r \cos(\theta)^2 \sin(\theta)^2 J^4 + 24 r^5 \sin(\theta)^2 J^2) / (r^2 \sin(\theta)^2 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^3) + (2 M - r) (2 r^3 M^2 + 8 \sin(\theta)^2 J^2 M - r^4 M - 4 r \sin(\theta)^2 J^2 - 16 r \cos(\theta)^2 J^2)}{r^2 \sin(\theta)^2 (2 r^3 M - 16 \sin(\theta)^2 J^2 - r^4)^2}$$


(%i47) ev(ratsimp(Jphi),r);

(%o47) 
$$(384 r^3 \sin(\theta)^2 J^2 M^3 + ((- 544 r^4 \sin(\theta)^2 - 64 r^4 \cos(\theta)^2) J^2 - 768 \sin(\theta)^4 J^4) M^2 + ((256 r^5 \sin(\theta)^2 + 64 r^5 \cos(\theta)^2) J^2 - 256 r \sin(\theta)^4 J^4) M + 384 r^2 \sin(\theta)^4 J^4 + (- 40 r^6 \sin(\theta)^2 - 16 r^6 \cos(\theta)^2) J^2) / (8 r^{11} \sin(\theta)^2 M^3 + (- 192 r^8 \sin(\theta)^4 J^2 - 12 r^{12} \sin(\theta)^2) M^2 + (1536 r^5 \sin(\theta)^6 J^4 + 192 r^9 \sin(\theta)^4 J^2 + 6 r^{13} \sin(\theta)^2) M - 4096 r^2 \sin(\theta)^8 J^6 - 768 r^6 \sin(\theta)^6 J^4 - 48 r^{10} \sin(\theta)^4 J^2 - r^{14} \sin(\theta)^2)$$


(%i48) DivE_p: ratsimp(ev(at(DivE, [M=2, J=1, theta=%pi/2])));

(%o48) 
$$\frac{8 r^6 - 64 r^5 + 192 r^4 - 896 r^2 + 1536 r}{r^{12} - 12 r^{11} + 48 r^{10} - 64 r^9 + 48 r^8 - 384 r^7 + 768 r^6 + 768 r^4 - 3072 r^3 + 4096}$$


(%i49) Jr_p: ratsimp(ev(at(Jr, [M=2, J=1, theta=%pi/2])));

(%o49) 
$$\frac{88 r^6 - 928 r^5 + 3264 r^4 - 3840 r^3 + 384 r^2 - 3072 r + 6144}{r^{12} - 8 r^{11} + 16 r^{10} + 32 r^8 - 128 r^7 + 256 r^4}$$


(%i50) Jtheta_p: ratsimp(ev(at(Jtheta, [M=2, J=1, theta=%pi/2])));

(%o50) 
$$-\frac{48}{r^8 - 2 r^7 - 4 r^6 - 8 r^5}$$

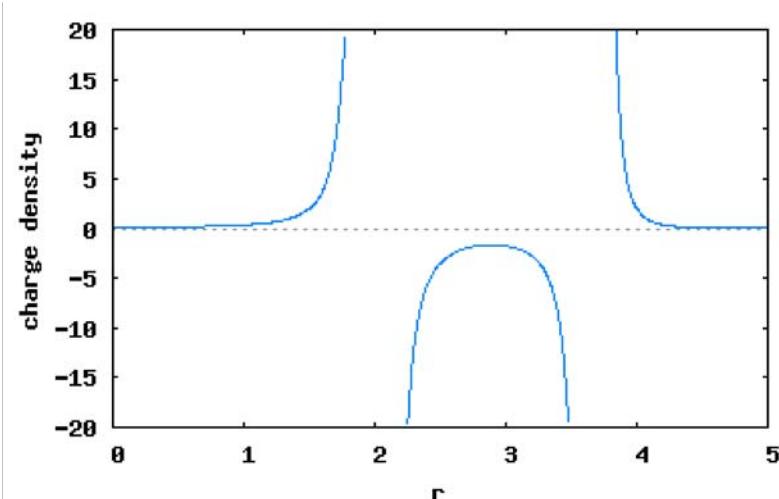

(%i51) Jphi_p: ratsimp(ev(at(Jphi, [M=2, J=1, theta=%pi/2])));
```

$$(\% o 51) \frac{40 r^6 - 512 r^5 + 2176 r^4 - 3072 r^3 - 384 r^2 + 512 r + 3072}{r^{14} - 12 r^{13} + 48 r^{12} - 64 r^{11} + 48 r^{10} - 384 r^9 + 768 r^8 + 768 r^6 - 3072 r^5 + 4096 r^2}$$

(%i52)

```
wxplot2d([DivE_p], [r,0,5], [y,-20,20], [gnuplot_preamble, "set zeroaxis;"], [xlabel, "r"], [ylabel, "charge density"])$
```

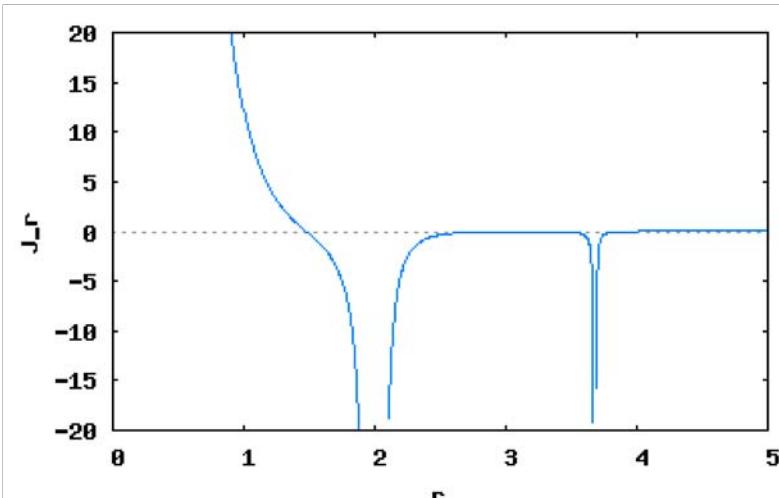
Output file "C:/Documents and Settings/Administrator/maxout.png".



(%i53)

```
wxplot2d([Jr_p], [r,0,5], [y,-20,20], [gnuplot_preamble, "set zeroaxis;"], [xlabel, "r"], [ylabel, "J_r"])$
```

Output file "C:/Documents and Settings/Administrator/maxout.png".

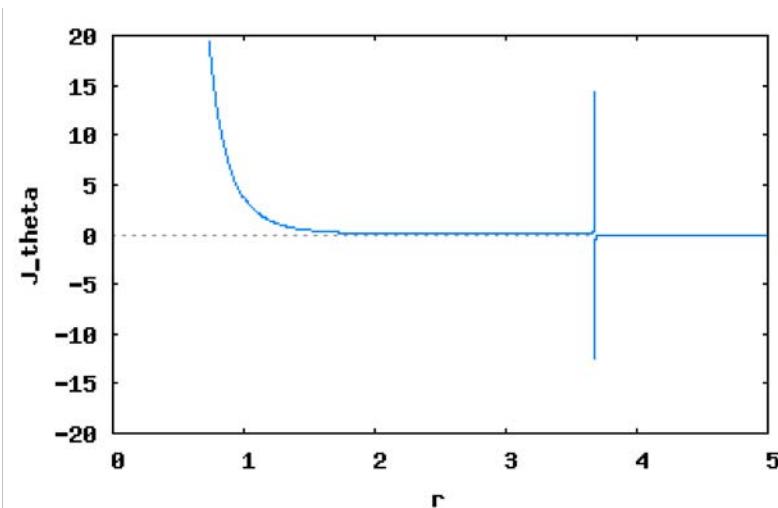


(%i54)

```
wxplot2d([Jtheta_p], [r,0,5], [y,-20,20], [gnuplot_preamble, "set zeroaxis;"], [xlabel, "r"], [ylabel, "J_theta"])$
```

Output file "C:/Documents and Settings/Administrator/maxout.png".

(%)t54)

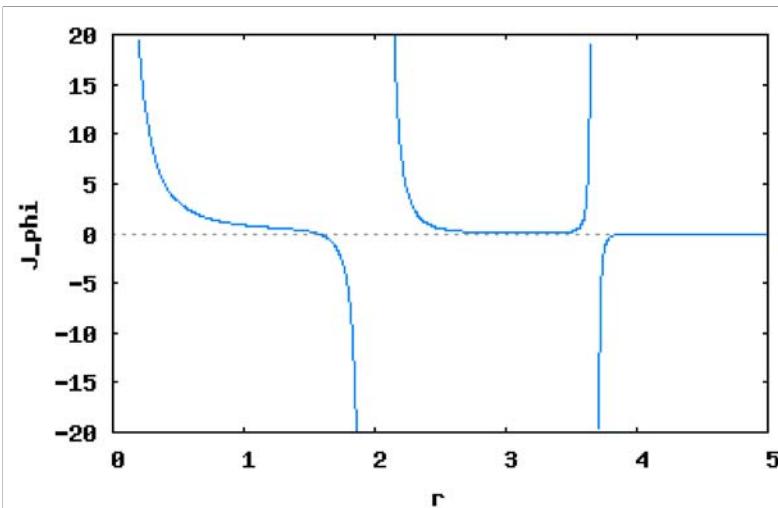


(%)i55)

```
wxplot2d([Jphi_p], [r,0,5], [y,-20,20], [gnuplot_preamble, "set zeroaxis;"], [xlabel, "r"], [ylabel, "J_phi"])$
```

Output file "C:/Documents and Settings/Administrator/maxout.png".

(%)t55)



(%)i56) DivE_p: ratsimp(ev(at(DivE, [M=1, J=2, theta=%pi/2])));

$$(%)o56) \frac{32 r^6 - 128 r^5 + 192 r^4 - 14336 r^2 + 12288 r}{r^{12} - 6 r^{11} + 12 r^{10} - 8 r^9 + 192 r^8 - 768 r^7 + 768 r^6 + 12288 r^4 - 24576 r^3 + 262144}$$

(%)i57) Jr_p: ratsimp(ev(at(Jr, [M=1, J=2, theta=%pi/2])));

$$(%)o57) \frac{352 r^6 - 1856 r^5 + 3264 r^4 - 1920 r^3 + 6144 r^2 - 24576 r + 24576}{r^{12} - 4 r^{11} + 4 r^{10} + 128 r^8 - 256 r^7 + 4096 r^4}$$

(%)i58) Jtheta_p: ratsimp(ev(at(Jtheta, [M=1, J=2, theta=%pi/2])));

$$(%)o58) -\frac{192 r - 192}{r^9 - 2 r^8 + 64 r^5}$$

(%)i59) Jphi_p: ratsimp(ev(at(Jphi, [M=1, J=2, theta=%pi/2])));

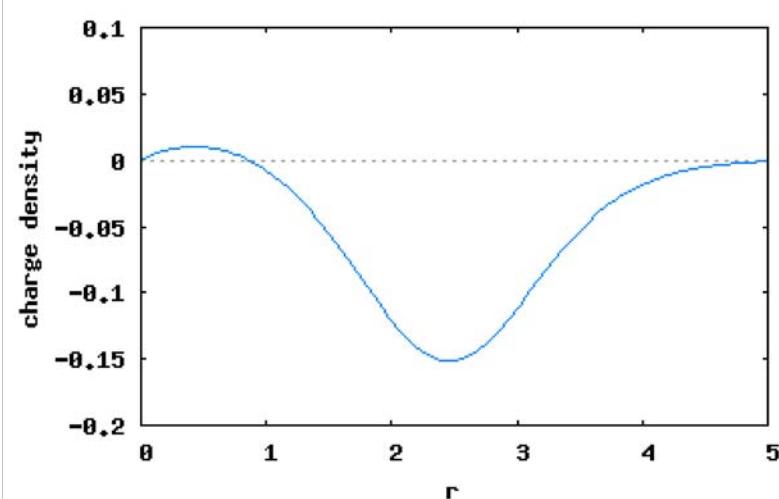
$$(\% o 59) \frac{160 r^6 - 1024 r^5 + 2176 r^4 - 1536 r^3 - 6144 r^2 + 4096 r + 12288}{r^{14} - 6 r^{13} + 12 r^{12} - 8 r^{11} + 192 r^{10} - 768 r^9 + 768 r^8 + 12288 r^6 - 24576 r^5 + 262144 r^2}$$

(%i60)

```
wxplot2d([DivE_p], [r,0,5], [y,-.2,.1], [gnuplot_preamble, "set zeroaxis;"], [xlabel, "r"], [ylabel, "charge density"])$
```

Output file "C:/Documents and Settings/Administrator/maxout.png".

(%t60)

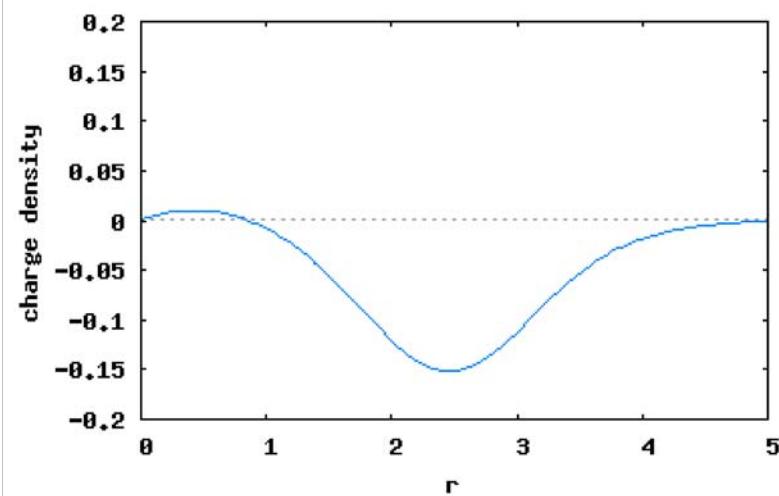


(%i61)

```
wxplot2d([DivE_p], [r,0,5], [y,-.2,.2], [gnuplot_preamble, "set zeroaxis;"], [xlabel, "r"], [ylabel, "charge density"])$
```

Output file "C:/Documents and Settings/Administrator/maxout.png".

(%t61)

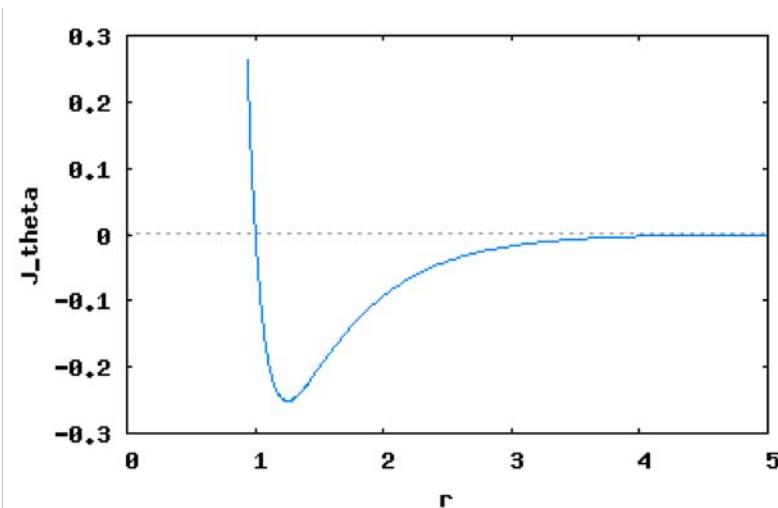


(%i62)

```
wxplot2d([Jtheta_p], [r,0,5], [y,-.3,.3], [gnuplot_preamble, "set zeroaxis;"], [xlabel, "r"], [ylabel, "J_theta"])$
```

Output file "C:/Documents and Settings/Administrator/maxout.png".

(t62)

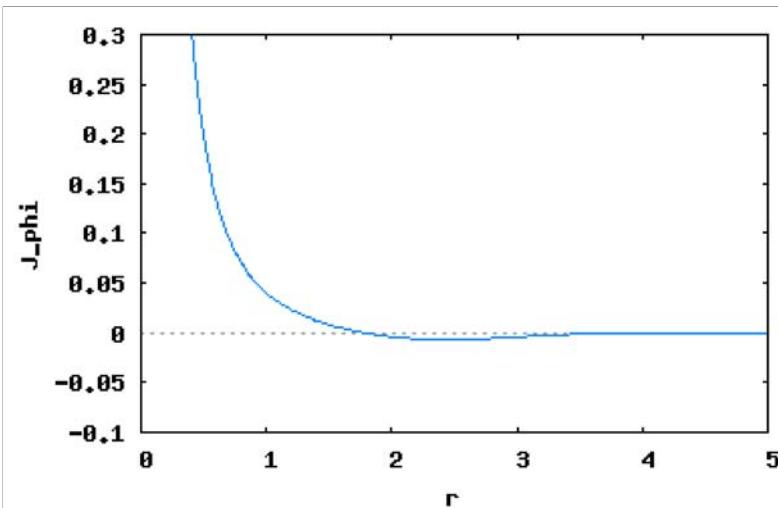


(i63)

```
wxplot2d([Jphi_p], [r,0,5], [y,-.1,.3], [gnuplot_preamble, "set zeroaxis;"],  
[xlabel, "r"], [ylabel, "J_phi"])$
```

Output file "C:/Documents and Settings/Administrator/maxout.png".

(t63)



(i64)